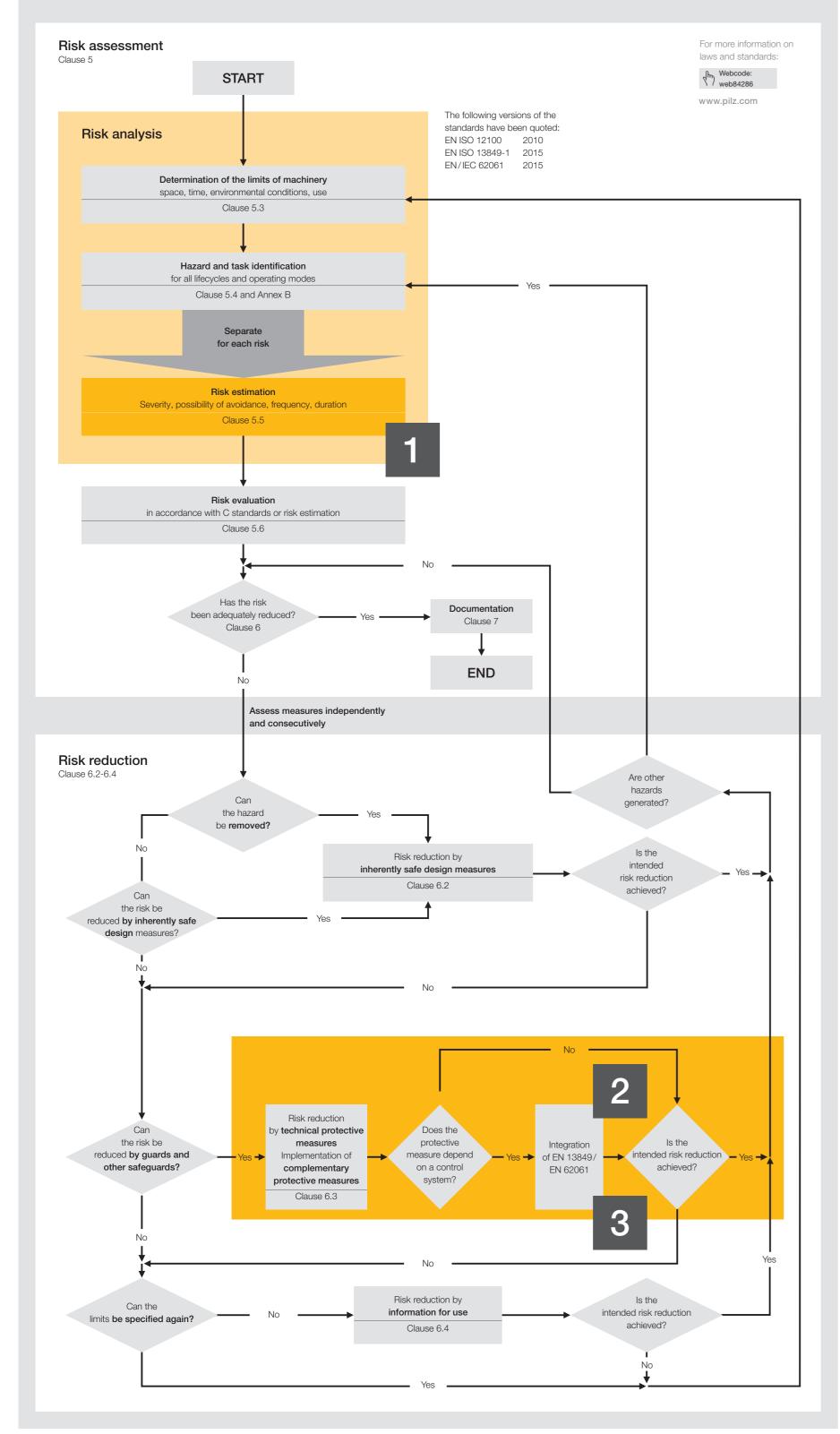
Functional safety EN ISO 12100, EN ISO 13849 and EN/IEC 62061

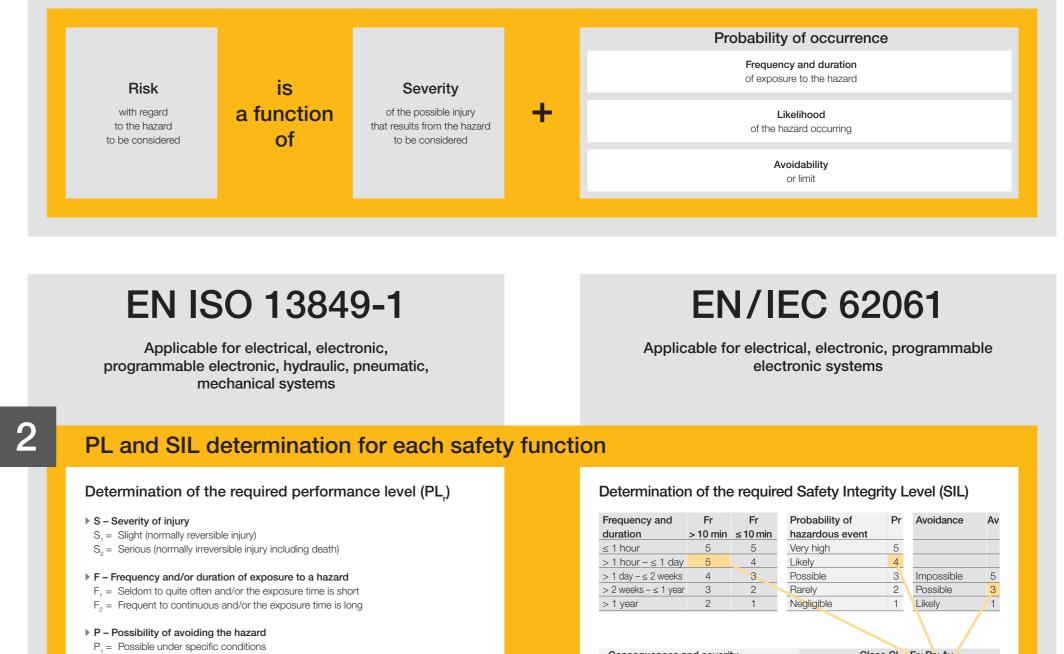
PILZ THE SPIRIT OF SAFETY

EN ISO 12100 Risk assessment and risk reduction



EN ISO 12100

Risk assessment based on the following risk parameters for each danger zone

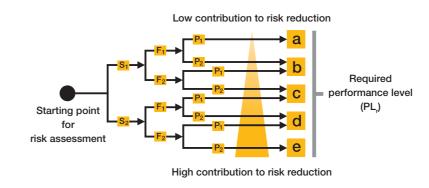


Glossary of te	erms				
 B_{tod} Number of cycles of products before 10% of the product range fails "dangerously" Category (CAT) 	 DC_{avg} Average diagnostic coverage Fault State of an item character- ized by inability to perform a 	 n_{op} Mean frequency of operation per annum Performance level (PL) Discrete level to specify the 	 Safety function Function of the machine whose failure can result in an immediate increase of the risk(s) 	integrity level that is intended to maintain the safe condition of the machine or to prevent an immediate increase of the risk(s)	Verification Confirmation by examina- tion and by provision of a certificate stating that the requirements of the specification are met
Classification of the safety- related parts of a control system in respect of their resistance to faults and their subsequent behaviour in the	required function, excluding the inability during preventive maintenance or other planned actions, or due to lack of external resources	ability of safety-related parts of control systems to perform a safety function under foreseeable conditions	Safety Integrity Level (SIL) Discrete level (one out of a possible four) for specifying the safety integrity of the safety functions to be al-	 SRECS Safety-Related Electrical Control System SRP/CS – Safety-Related 	
fault condition, and which is achieved by the structural arrangement of the parts, fault detection and/or by their reliability	 λ Average probability of failure λ_p Dangerous failure rate 	Performance level, required (PL,) Performance level (PL) in order to achieve the required risk reduction for each safety function	located to the E/E/PE system, where SIL 3 (SIL 4 in the process industry) has the highest level of safety integrity and SIL 1 has the lowest	Part of a Control System Part of a control system that responds to safety- related input signals and generates safety-related output signals	
▶ CCF	Daligerous failure fale	TUTION	Safety validation	output signais	
Common cause failure	▶ λ_s Safe failure rate	PFH _D Probability of dangerous feiture part hour	Confirmation by examina- tion and by provision of a	Subsystem Entity of the top-level evolution of the	
Diagnostic coverage (DC) Measure for the effective- ness of diagnostics, may be determined as the ratio of the failure rate of detected dangerous failures and the failure rate of total dangerous failures	 Mission time Period of time covering the intended use of the SRP/CS MTTF_D Mean time to dangerous failure 	 Failure per hour Risk Combination of the probability of occurrence of harm and the severity of that harm 	 certificate stating that special requirements for a specific intended use are met SRCF – Safety-Related Control Function Control function implemented by an SRECS with a specified 	architectural design of the SRECS where a failure of any subsystem will result in a failure of a safety-related control function	



Probability of occurrence of the hazardous event

A low probability can reduce the PL by one level



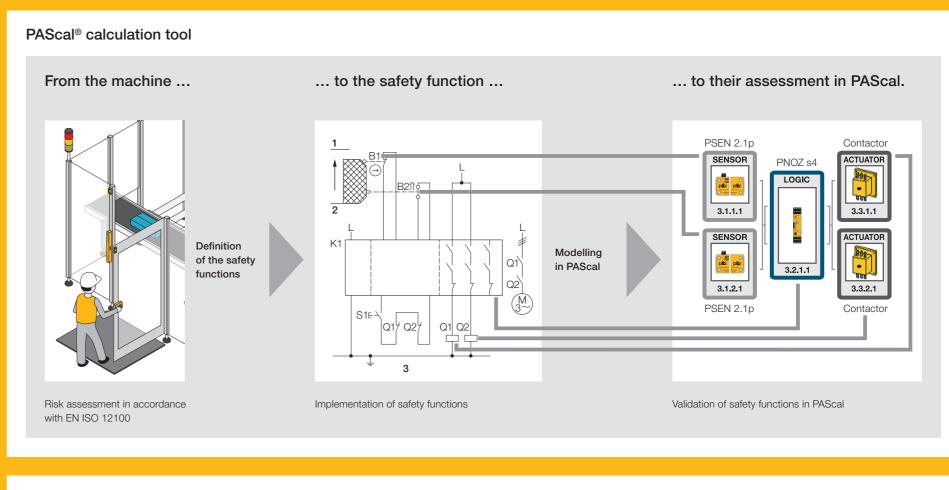
Consequences and sevenity		Class CI = FI+PI+AV				
	Se	3-4	5-7	8-10	11-13	14-15
Death, losing an eye or arm	4	SIL 2	SIL 2	SIL 2	SIL 3	SIL 3
Permanent, losing fingers	3		OM	SIL 1	SIL 2	SIL 3
Reversible, medical attention	2			OM	SIL 1	SIL 2
Reversible, first aid	1				OM	SIL 1
		OM = other measures recommended				

Calculation of the safety function (e.g. with PAScal®)

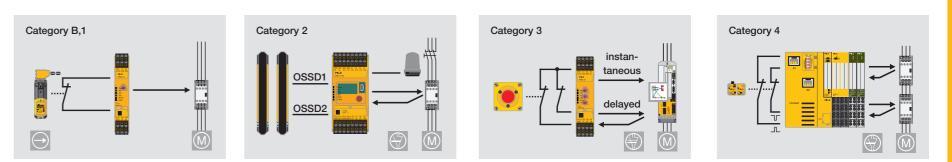
Necessary safety performance data

3

EN ISO 13849-1			EN/IEC 62061			
Data provided by the manufacturer	Data provided by the user				Data provided by the manufacturer	Data provided by the user
PFH, PL Category, T _M	-	Units with internal diagnostics Safety control, safety relay		PFH SIL T _M	_	
MTTF _D	DC, CCF, Category	Units without internal	No wearing components	Sensors	$\begin{array}{c} MTTF_{D} \\ \lambda_{d} \\ \lambda_{s} \end{array}$	DC, CCF, Subsystem type
B10 _d	DC, CCF, Category, n _{op}	diagnostics	With wearing components	EMERGENCY STOPs, relays, switches, valves	$B10_d$ λ_d λ_s	DC, CCF, Subsystem type, n _{op}



Specification of categories - examples of solutions



The measures outlined on this sheet are simplified descriptions and are intended to provide an overview of the standards EN ISO 12100, EN ISO 13849-1 and EN / IEC 62061. Detailed understanding and correct application of all relevant standards and directives are needed for validation of safety circuits. As a result, we cannot accept any liability for omissions or incomplete information.



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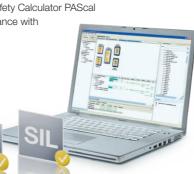
engineering: from risk assessment through to

qualification programme guarantees enhanced

Determine the safety levels of safety functions with ease - with the Safety Calculator PAScal you have a handy calculation tool to verify functional safety in accordance with EN ISO 13849-1 and EN/IEC 62061.

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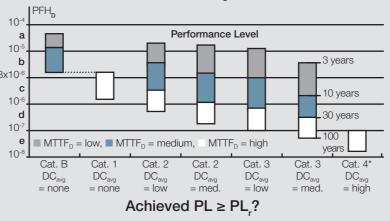


The solutions illustrated here are provided purely by way of example.

Probability of a dangerous failure per hour - comparison PL/SIL

Performance Level (PL) in accordance with EN ISO 13849-1

Relationship between the categories DC, MTTF_n and PL



* In Cat. 4, MTTF_{D} up to 2,500 a is possible

Safety Integrity Level (SIL) in accordance with EN / IEC 62061

